# ENGINE: an Enhancer-Gene Interaction dEtection method using robust feature extraction

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co-binding active region already exists, but regulated by other factors: H3K4me1, EP300, other competitive factors.

We have enhancer-gene pairs, however, the region is quite large(2K or more), however, cobinding region may limited a region less than 100bp or even shorter.

DNase footprinting is also a good signatures to infer TF binding, but not very reliable, and people usually use the hotspot region to intersect FIMO identified binding regions.



# Difficulties

Given we have histone mark and other TF binding signal, it still has difficulties:

- Size of interaction region varies, Known methods: segementation (chromHMM and segway)
- No information of interaction site
- Two regions both have specific regulatory signal, No good methods to extract features.

Is it possible to identify robust features based on signals on A and B regions?

## Feature extraction and recognation

Object recognition and pattern matching are popular in Computer vision.



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#### RS distribution:







H3k4me2

H3k4me3









P300













## RandomForest

### AUC:0.958, feature importance:



rf.all

## Discussion

• Too good to be true? size bias? feature extraction black box?



- computational intensity
- Biological meaningful? How to link the extracted features with functions?
- Integrate the previous Kmer co-occurence feature.
- Evaluation?

## Supplementary

size vs #features:



positive set; negative set

The number of histone mark peaks overall in positive region is more than that in negative region.







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## Peak size comparison

We also compared the smalled and biggest peaks in these around region.



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# Signal

Limitation of data: peaks called, especially with replicas, there are no uniform peaks calling peaks, which results in the overlap of peak region.

Using the signal, but we need to face:

No good way to segment the 3d interaction region into features: no fixed-window, varied region size(sometime need.

idea is to convert the AB region feature into a image like feature matrix and then use computer vision method to extract features

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